

Assignment 10 and optional part–Computation of homoclinic orbits of the equilibrium points

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1 Restricted Three-Body Problem

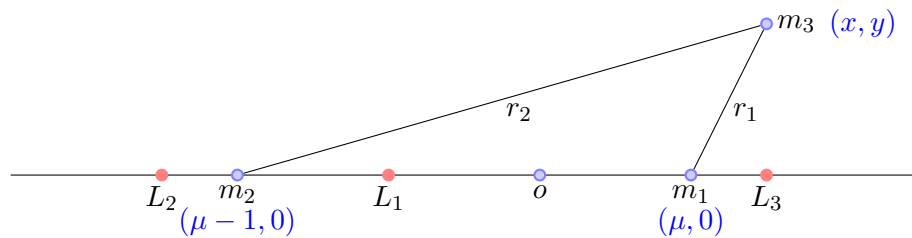


Figure 1: Restricted Three-Body Problem

The equations of motion are:

$$\begin{cases} x'' - 2y' = \Omega_x \\ y'' + 2x' = \Omega_y \end{cases} \quad (1)$$

And,

$$\Omega(x, y) = \frac{(x^2 + y^2)}{2} + \frac{1 - \mu}{r_1} + \frac{\mu}{r_2} + \frac{\mu(1 - \mu)}{2} \quad (2)$$

Here:

$$\begin{cases} \mu &= \frac{m_2}{m_1+m_2} \\ r_1 &= \sqrt{(x-\mu)^2+y^2} \\ r_2 &= \sqrt{(x-\mu+1)^2+y^2} \end{cases} \quad (3)$$

Let:

$$\begin{cases} x_1 &= x \\ x_2 &= y \\ x_3 &= x' \\ x_4 &= y' \end{cases} \quad (4)$$

The RTBP is expressed as:

$$\begin{cases} f_1 &= x'_1 = x_3 \\ f_2 &= x'_2 = x_4 \\ f_3 &= x'_3 = 2x_4 + \Omega_{x_1} \\ f_4 &= x'_4 = -2x_3 + \Omega_{x_2} \end{cases} \quad (5)$$

Where,

$$\begin{cases} \Omega_{x_1} &= x_1 - \frac{(1-\mu)(x_1-\mu)}{r_1^3} - \frac{\mu(x_1-\mu+1)}{r_2^3} \\ \Omega_{x_2} &= x_2 \left(1 - \frac{1-\mu}{r_1^3} - \frac{\mu}{r_2^3}\right) \end{cases} \quad (6)$$

2 Equilibrium points— L_1, L_2, L_3

The position of L_1 is:

$$x_{L_1} = \mu - 1 + \xi \quad (7)$$

where,

$$\begin{aligned} f(\xi) &= \left(\frac{\mu(1-\xi)^2}{3-2\mu-\xi(3-\mu-\xi)} \right)^{\frac{1}{3}} \\ \xi_0 &= \left(\frac{\mu}{3(1-\mu)} \right)^{\frac{1}{3}} \\ \xi_{n+1} &= f(\xi_n) \end{aligned}$$

The position of L_2 is:

$$x_{L_2} = \mu - 1 - \xi \quad (8)$$

where,

$$f(\xi) = \left(\frac{\mu(1+\xi)^2}{3-2\mu+\xi(3-\mu+\xi)} \right)^{\frac{1}{3}}$$

$$\xi_0 = \left(\frac{\mu}{3(1-\mu)} \right)^{\frac{1}{3}}$$

$$\xi_{n+1} = f(\xi_n)$$

The position of L_3 is:

$$x_{L_3} = \mu + \xi \tag{9}$$

where,

$$f(\xi) = \left(\frac{(1-\mu)(1+\xi)^2}{1+2\mu+\xi(2+\mu+\xi)} \right)^{\frac{1}{3}}$$

$$\xi_0 = 1 - \frac{7}{12}\mu$$

$$\xi_{n+1} = f(\xi_n)$$

3 result

$\mu = 0.008$, $L_3 = 1.0033333053755920$

The first crossing with Poincare section $y=0$, the point is:

$$\begin{pmatrix} 0.59826229280258836 \\ 2.9575936557792854^{-14} \\ -0.26780932584763739 \\ 0.80590085785342314 \end{pmatrix}$$

The unstable manifold of L_3 , with initial condition: $L_3 - 10^{-6} \cdot \vec{v}$.

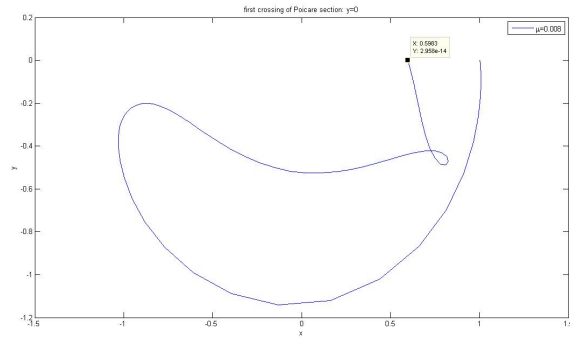


Figure 2: $\mu = 0.008$, 1st-crossing

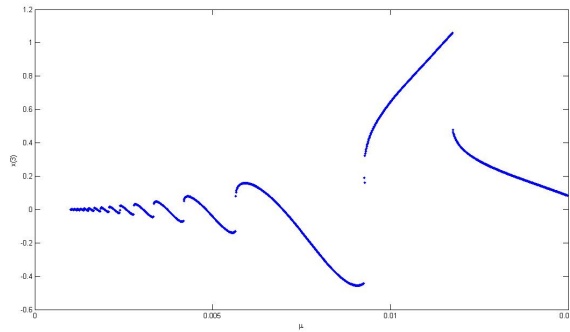


Figure 3: x' V.s μ in the interval (0.001,0.015)

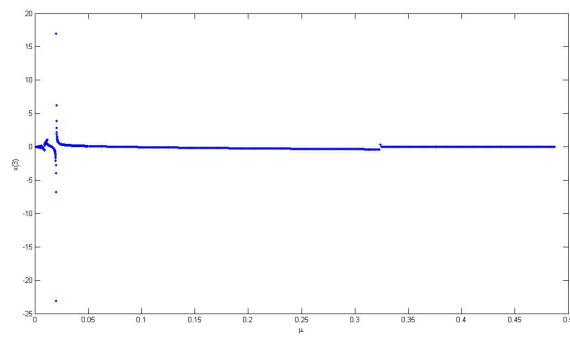


Figure 4: x' V.s μ in the interval (0.001,0.5)

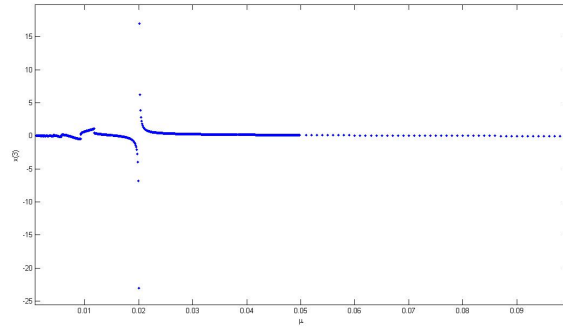


Figure 5: x' V.s μ in the interval (0.001,0.1)

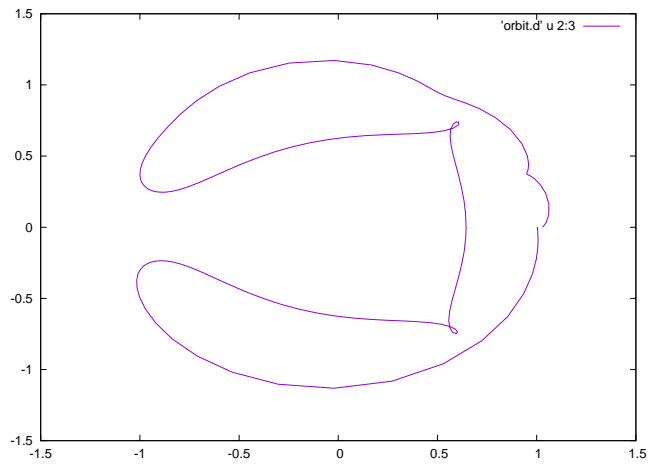


Figure 6: $\mu = 6.96499999^{-3}$, 2nd crossing

4 Code

Main function:

```
implicit real*8 (a-h,o-z)
parameter (n=4)
common/param/xmu
dimension x(n),oa(n,n),rr(n),ri(n),vr(n,n),vi(n,n)
open(10,file='orbit.d',status='unknown')
open(11,file='relation.d',status='unknown')
ti=0
T=0.3138977039438897d01
tmax=20.d0*T
np=10
p=-1
write(*,*)'xincmu:'
read(*,*) xincmu
write(*,*)'xmuLow:'
read(*,*) xmuLow
write(*,*)'xmuUpp:'
read(*,*) xmuUpp
m=(xmuUpp-xmuLow)/xincmu-2
write (*,*)'m:', m
do j=1,m
  xmu=xmuLow+j*xincmu
  call peq(xmu,xl1,xl2,xl3,c11,c12,c13)
  call jacobiA(xmu,xl3,n,oa)
  call vapvep(oa,n,rr,ri,vr,vi)
  x(1)=xl3
  x(2)=0.d0
  x(3)=0.d0
  x(4)=0.d0
  idir=dsign(1.d0,rr(3))
  x(1)=p*vr(1,3)*1.d-6+x(1)
  x(2)=p*vr(2,3)*1.d-6+x(2)
  x(3)=p*vr(3,3)*1.d-6+x(3)
  x(4)=p*vr(4,3)*1.d-6+x(4)
  call poinc1(n,x,tfinal,idir)
  write(11,*)xmu,x(1),x(3)
enddo
end
```

C

```
*****
```

C

```

C
*****

SUBROUTINE POINC1(n,YI,tfinal,idirorig)
IMPLICIT REAL*8 (A-H,O-Z)
DIMENSION YI(n),YF(n),DGG(n),F(n)
icont=0
idir=idirorig
ti=0.d0
C DETERMINATION OF THE FIRST PASSAGE OF THE ORBIT THROUGH
y=0
CALL SECCIO(YI,GG,DGG)
IF(DABS(GG).LT.1.D-9)GG=0.d0
GA=GG
hab=.1e-16
hre=.1e-16
pabs=dlog10(hab)
prel=dlog10(hre)
istep=1
pas=5d0
ht=0.d0
t=ti
1   tmax=t+idir*pas
CALL taylor_f77_eq_rtbp_(t,yi,idir,istep,pabs,prel,
& tmax,ht,iordre,ifl)
CALL SECCIO(YI,GG,DGG)
IF(GG*GA.LT.0.DO)go to 22
write(10,*)t,(yi(ii),ii=1,4)
GA=GG
GO TO 1
C
C REFINEMENT OF THE INTERSECTION POINT YF(*) USING NEWTON
METHOD
C TO GET A ZERO OF THE FUNCTION GG (SEE SUBROUTINE SECCIO)
C
22   continue
icont=icont+1
if (icont.gt.20)then
write(*,*)'problems finding the section'
return
endif
CALL FIELD(T,YI,N,F)
P=0.DO
DO 3 I=1,N
3   P=P+F(I)*DGG(I)
H=-GG/P
if (h.ge.0.d0)idir=1

```

```

if (h.lt.0.d0)idir=-1
tmax=t+h

CALL taylor_f77_eq_rtbp_(t,yi,idir,istep,pabs,prel,
& tmax,ht,iordre,ifl)
CALL SECCIO(YI,GG,DGG)
IF(DABS(GG).GT.1.D-13)GO TO 22
DO 4 I=1,N
4 YF(I)=YI(I)
tfinal=t
write(10,*)t,(yf(ii),ii=1,4)
return
end

C
*****
C
*
C THE SURFACE g OF SECTION,IN THIS CASE
C INPUT PARAMETERS:
C Y(*) POINT
C OUTPUT PARAMETERS:
C GG FUNCTION THAT EQUATED TO 0 GIVES THE
C SURFACE OF
C SECTION
C DGG(*) GRADIENT OF FUNCTION GG
C
*
C
*****

SUBROUTINE SECCIO(Y,GG,DGG)
IMPLICIT REAL*8(A-H,O-Z)
DIMENSION Y(4),DGG(4)
GG=Y(2)
DO 1 I=1,4
1 DGG(I)=0.DO
DGG(2)=1.d0
RETURN
END

C
C
*****

```



```

C
C   EQS OF MOTION IN synodical VARIABLES
C   X           TIME
C   Y(*)        POINT (Y(1),Y(2),...Y(n))
C   NEQ         NUMBER OF EQUATIONS
C   OUTPUT PARAMETERS:
C   F(*)        VECTOR FIELD
C
C
C

```

```

*****

```

```

subroutine field(t,x,neq,f)
implicit real*8 (a-h,o-z)
common/param/xmu
dimension x(neq),f(neq)
umu=1.-xmu
d1=x1-xmu
d2=x1+umu
r12=d1*d1+x2*x2
r22=d2*d2+x2*x2
r0=sqrt(r12)
r1=sqrt(r22)
r032=r12*r0
r132=r22*r1
omex=x1-(umu*(-xmu+x1)/r032)-(xmu*(x1+umu)/r132)
omey=x2*(1.-(umu/r032)-(xmu/r132))
f(1)=x(3)
f(2)=x(4)
f(3)=2*x(4)+omex
f(4)=-2*x(3)+omey
return
end

```

```

C

```

```

*****

```

```

C

```

```

C

```

```

*****

```

```

subroutine jacobiA(xmu,x,n,oa)
implicit real*8(a-h,o-z)
dimension oa(n,n)
umu=1.d0-xmu
x1=x
xd1=dabs(x1-xmu)
xd2=dabs(x1+umu)
r032=xd1**3

```

```

r132=xd2**3
r052=xd1**5
r152=xd2**5
xa=3*umu*(-xmu+x1)/r052
xb=3*xmu*(x1+umu)/r152
omexx=1.d0-umu/r032+xa*(-xmu+x1)-xmu/r132+xb*(x1+umu
)
omeyy=1.d0-umu/r032-xmu/r132
oa(1,1)=0.d0
oa(1,2)=0.d0
oa(1,3)=1.d0
oa(1,4)=0.d0
oa(2,1)=0.d0
oa(2,2)=0.d0
oa(2,3)=0.d0
oa(2,4)=1.d0
oa(3,1)=omexx
oa(3,2)=0.d0
oa(3,3)=0.d0
oa(3,4)=2.d0
oa(4,1)=0.d0
oa(4,2)=omeyy
oa(4,3)=-2.d0
oa(4,4)=0.d0
return
end

```

5 optional part—some particular cases

5.1 The curve (μ, x)

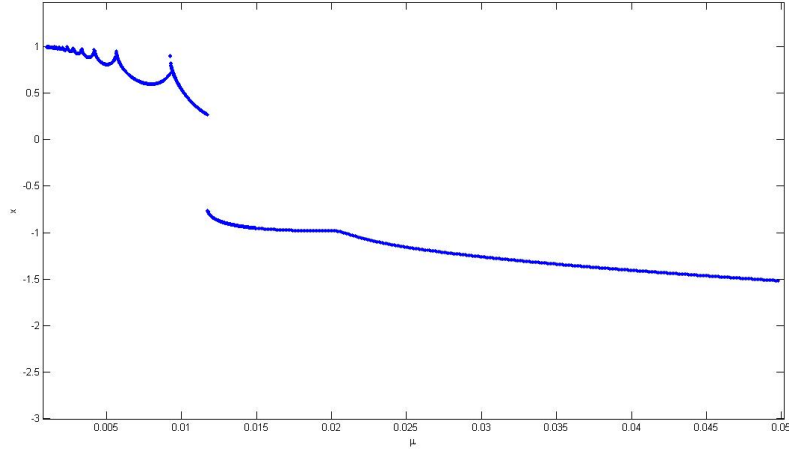


Figure 7: x V.s μ in the interval (0.001,0.015)

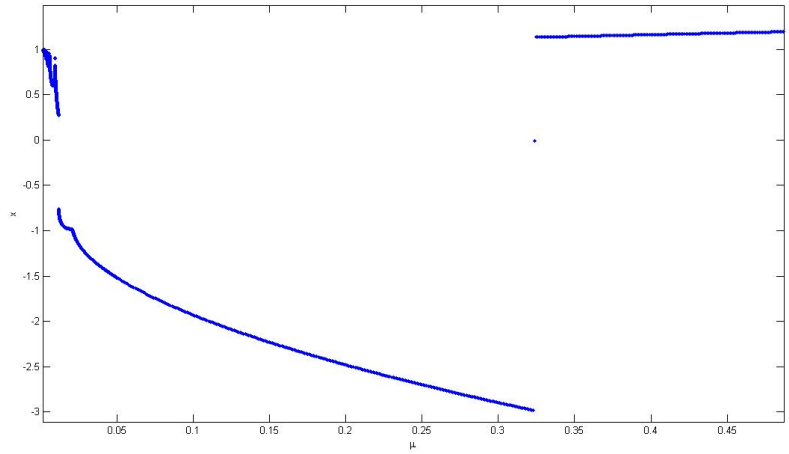


Figure 8: x V.s μ in the interval (0.001,0.5)

5.2 Some fixed μ and comments

From the relationship between μ and x , i.e. figures 7 and 8, we can see in interval $\mu \in (0.001, 0.5)$, it is separated into three parts by $\mu \approx 0.01174$ and $\mu \approx 0.3245$. In the first part, the value of x is around 1, it means the first crossing is closed to the equilibrium point L_3 , which is showed in figures

9,?? and 11. The overall trend of first crossing point goes farther away from the L_3 as μ increasing, despite the oscillations at the beginning. When μ is bigger than 0.01174, it reaches the second part, where the first crossing is around -1 . We can see the examples from figures 12, 13 and 14. In the third part, the first crossing is around 1 again.

From the relationship between μ and x' , i.e. figures 3 and 4, we can see when μ is smaller than 0.01, there are several jumps in the x' . i.e. in one point (the first crossing), there are two different x' , which brings a small loop. And this loop is symmetric with respect to x-axis, as showed in figure 10b ($\mu = 0.00567$, 2nd crossing). Besides, we can see, there is a singular point $\mu \approx 0.02$. It represents that the first-crossing collides with m_2 .

For the μ is equal to 0.0056, 0.00567, 0.0057 respectively.

For the μ is equal to 0.01179, 0.0159375, 0.083 respectively.

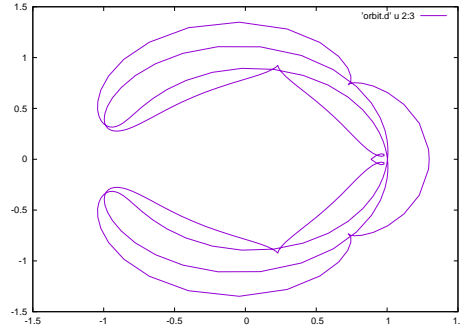


Figure 9: $\mu = 0.0056$

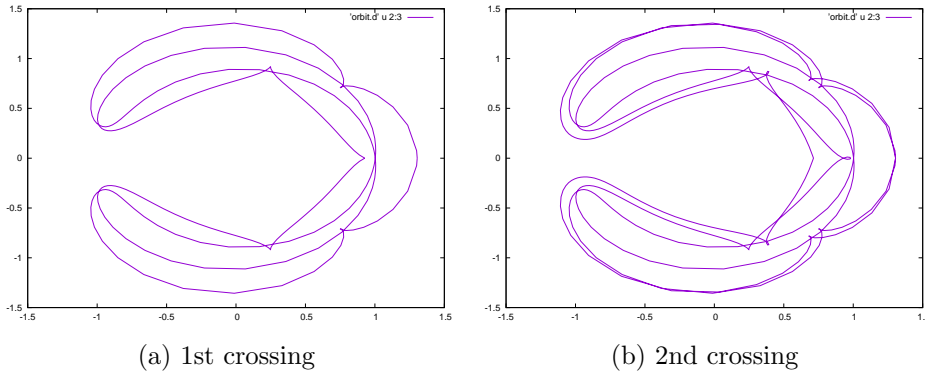


Figure 10: $\mu = 0.00567$

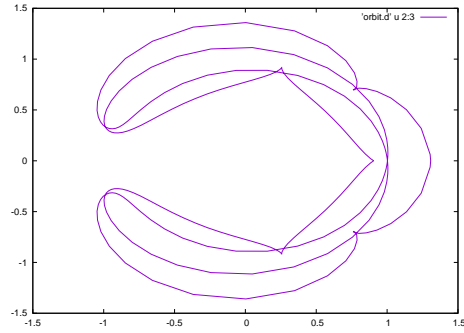


Figure 11: $\mu = 0.0057$

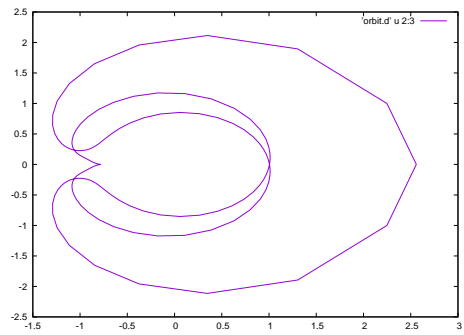


Figure 12: $\mu = 0.01179$

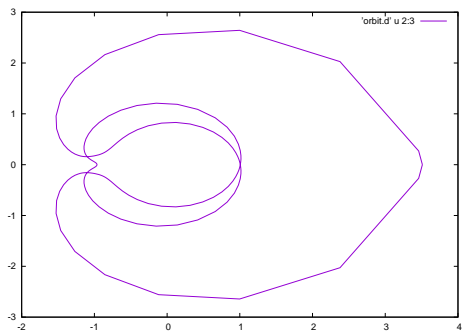


Figure 13: $\mu = 0.0159375$

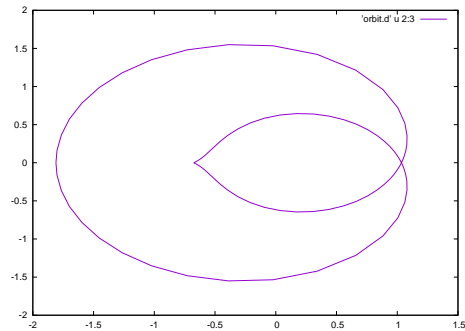


Figure 14: $\mu = 0.083$

6 Code

Main function:

```

implicit real*8 (a-h,o-z)
parameter (n=4)
common/param/xmu
dimension x(n),oa(n,n),rr(n),ri(n),vr(n,n),vi(n,n)
open(10,file='orbit.d',status='unknown')
open(11,file='relation.d',status='unknown')
ti=0
T=0.3138977039438897d01
tmax=20.d0*T
np=10
p=-1
write(*,*)'mu:'
read(*,*)xmu

call peq(xmu,xl1,xl2,xl3,cl1,cl2,cl3)
call jacobiA(xmu,xl3,n,oa)
call vapvep(oa,n,rr,ri,vr,vi)
do k=1,2
  p=-1*p
  write(*,*)'p:', p
  do j=3,4
    x(1)=xl3
    x(2)=0.d0
    x(3)=0.d0
    x(4)=0.d0
    idir=dsign(1.d0,rr(j))
    write(*,*)'idir:', idir
    x(1)=p*vr(1,j)*1.d-6+x(1)

```

```

x(2)=p*vr(2,j)*1.d-6+x(2)
x(3)=p*vr(3,j)*1.d-6+x(3)
x(4)=p*vr(4,j)*1.d-6+x(4)
write(*,*) 'Initial t:'
write(*,*) ti
write(*,*) 'Initial cond:'
write(*,*) (x(ii),ii=1,n)
write(*,*) 'm times crossing'
read(*,*) m
do i=1,m
    call poinc1(n,x,tfinal,idir)
    t=tfinal+t
    write(*,*) 't:'
    write(*,*) t
enddo
write(10,90)
format()
enddo
enddo
end

```

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