

Numerics of Dynamical Systems

Assignment 10

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1 Programme

main_rtbp_flow10.f was used for the plots of (x_{μ}, x') or (x_{μ}, x) .

Since vebrep from package_alg calculates as eigenvalues almost only zeros I used always the first eigenvector.

Listing 1: main_rtbp_flow10.f

```
c*****
c
c  MAIN_RTBP_FLOW9.f
c
c      We integrate the harmonic oscillator field with Taylor
c      from t=ti up to t=tmax
c      idir= +1 (integration forward in time); =-1 (backward)
c      np= number of intermediate points (apart from the initial one)
c      that we want to write on the file orbit.d. If np=1
c      only the initial and final points are written
c
c  input: xi, ti, tmax, idir, np
c*****
      implicit real*8 (a-h,o-z)
      parameter (n=4,m=4)
      dimension xi(n),x(n),O(m,m),A(n,n),RR(n),RI(n),VR(n,n),VI(n,n)
      dimension v(n),p(2),yf(n)
      common/param/xmu
      open(10,file='orbit.d',status='unknown')
      write(*,*) 'sign '
      read(*,*) iregion
      write(*,*) 'idir?'
      read(*,*) idir
      write(*,*) 'ncrossing?'
      read(*,*) ncrossing
      ti=0.d0
      tmax = 6.28
      np=30
      write(*,*) 'xmu?'
      read(*,*) xmu

      call peq(xmu,x11,x12,x13,c11,c12,c13)
      write(*,*) 'x13', x13
      write(*,*) 'c13', c13
```

```

C=c13
x(1)=x13
x(2)=0
x(3)=0
x(4)=0
call JacobiMatrix(n,x,xmu,A)
write(*,*) 'A'
  do i=1,n
    write(*,*) (A(i,j),j=1,n)
  enddo
call vapvep(A,n,RR,RI,VR,VI)

if(idir.gt.0) then
  do i=1,n
    if(RI(i).gt.0) then
      k=i
    endif
  enddo
else
  do i=1,n
    if(RI(i).lt.0) then
      k=i
    endif
  enddo
endif
k=1

do i=1,n
  v(i) = VR(i,k)
enddo
p(1) = RR(k)
write(*,*) 'Eigenvalue', p(1)
write(*,*) 'v', (v(i),i=1,n)
s = 1.d-6
  if(iregion.lt.0) then
    s = -s
  endif
x = x + s * v
write(*,*) 'initial_point', (x(i),i=1,n)

```

```

        call jacobi(x,C,xmu,n)

        ti=0
        do j = 1,ncrossing
        t=0.d0
            write(10,*)t,(x(i),i=1,n)
            call poinc1(j,xmu,n,m,x,yf,tfinal,idir,ti)
            ti = ti + tfinal
        end do
    end

C*****
c Input:
c n dimension of the vectors yi and yf
c yi initial point
c idirorig: +1 integration forwards in time; -1 backwards
c yf final point
c tfinal final time
c
C*****
        SUBROUTINE POINC1(j,xmu,n,m,YI,YF,tfinal,idirorig,ti)
        IMPLICIT REAL*8 (A-H,O-Z)
        DIMENSION YI(n),YF(n),DGG(n),F(n)
            icont=0
            idir=idirorig
c
c we assume initial time t=0.
c
c         ti=0.D0
C DETERMINATION OF THE FIRST PASSAGE OF THE ORBIT THROUGH y=0
C
        CALL SECCIO(YI,GG,DGG)
        IF (DABS(GG).LT.1.D-9)GG=0.d0
        GA=GG
        hab=.1e-16
        hre=.1e-16
        pabs=dlog10(hab)
        prel=dlog10(hre)
        istep=1
c reasonable step:
        pas=0.4d0

```

```

        ht=0.d0
        t=ti
c |tmax| must be big enough
1      tmax=t+idir*pas
        CALL taylor_f77_eq_rtbp_var_(t,yi,idir,istep,pabs,prel,
        & tmax,ht,iordre,ifl)
c computation of first integral to be done
C
        CALL SECCIO(YI,GG,DGG)
        IF(GG*GA.LT.0.D0)go to 22
        write(10,*)t,(yi(ii),ii=1,n)
        GA=GG
        GO TO 1
C
C   REFINEMENT OF THE INTERSECTION POINT YF(*) USING NEWTON'S METHOD
C   TO GET A ZERO OF THE FUNCTION GG (SEE SUBROUTINE SECCIO)
C
..22.....continue
        .....icont=icont+1
        .....if_(icont.gt.20)then
        .....write(*,*)'problems finding the section'
        .....stop
        .....endif
        .....CALL_FIELD(xmu,T,YI,N,F)
        .....P=0.D0
        .....DO_3_I=1,N
3.....P=P+F(I)*DGG(I)
        .....H=-GG/P
c_check_p_is_not_(or_very_close_to)_0:_to_be_done
        .....if_(h.ge.0.d0)idir=1
        .....if_(h.lt.0.d0)idir=-1
        .....tmax=t+h
c.....write(*,*)icont,' refining: h and time ',h,tmax
c.....write(*,*)'refining t point ',t,yi(1),yi(2)
        .....CALL_taylor_f77_eq_rtbp_var_(t,yi,idir,istep,pabs,prel,
        & tmax,ht,iordre,ifl)
        .....CALL_SECCIO(YI,GG,DGG)
        .....IF(DABS(GG).GT.1.D-13)GO_TO_22
        .....DO_4_I=1,N
4.....YF(I)=YI(I)
        .....tfinal=t

```

```

c_check_first_integral:_to_be_done
.....write(*,*)'tfinal point time ',tfinal
.....write(*,*)(yf(ii),ii=1,n)
.....write(10,*)t,(yf(ii),ii=1,n)
.....return
.....t=_tfinal
.....end

C*****
C.....*
C.....THE_SURFACE_g_OF_SECTION, IN THIS CASE
C.....INPUT_PARAMETERS:
C.....Y(*).....POINT
C.....OUTPUT_PARAMETERS:
C.....GG.....FUNCTION_THAT_EQUATED_TO_0_GIVES_THE_SURFACE_OF
C.....SECTION
C.....DGG(*).....GRADIENT_OF_FUNCTION_GG
C.....*
C*****
C.....SUBROUTINE_SECCIO(Y,GG,DGG)
C.....IMPLICIT_REAL*8(A-H,O-Z)
C.....DIMENSION_Y(2),DGG(2)
C.....GG=Y(2)
C.....DO_1_I=1,2
_1.....DGG(I)=0.D0
.....DGG(2)=1.d0
C.....RETURN
C.....END

C
C_FIELD.F
C
C*****
C.....EQS_OF_MOTION_IN_synodical_VARIABLES
C.....X.....TIME
C.....Y(*).....POINT_(Y(1),Y(2),....Y(n))
C.....NEQ.....NUMBER_OF_EQUATIONS
C.....OUTPUT_PARAMETERS:

```

```

C_____F(*)_____VECTOR_FIELD
C
C*****
_____subroutine _field (xmu, t, x, neq, f)
_____implicit _real*8_(a-h, o-z)
_____dimension _x(neq), f(neq)
c
_____umu=1.d0-xmu
_____d1=x(1)-xmu
_____d2=x(1)+umu
_____r12=d1*d1+x(2)*x(2)
_____r22=d2*d2+x(2)*x(2)
_____r0=dsqrt(r12)
_____r1=dsqrt(r22)
_____r032=r12*r0
_____r132=r22*r1
_____r052=r12*r032
_____r152=r22*r132
_____c1=-umu/r032-xmu/r132
_____c2=3.d0*umu/r052
_____c3=3.d0*xmu/r152
_____omex=x(1)-(umu*(-xmu+x(1))/r032)-(xmu*(x(1)+umu)/r132)
_____omey=x(2)*(1.d0-(umu/r032)-(xmu/r132))
_____omexx=c1+c2*d1*d1+c3*d2*d2+1.d0
_____omexy=c2*d1*x(2)+c3*d2*x(2)
_____omeyy=c1+(c2+c3)*x(2)*x(2)+1.d0
_____f(1)=x(3)
_____f(2)=x(4)
_____f(3)=2.*x(4)+omex
_____f(4)=-2.*x(3)+omey
_____return
_____end
c*****Jacobi-Matrix_of_x
_____subroutine _JacobiMatrix(n, x, xmu, A)
_____implicit _real*8_(a-h, o-z)
_____dimension _x(n), A(n, n)
c
_____umu=1.d0-xmu
_____d1=x(1)-xmu
_____d2=x(1)+umu
_____r12=d1*d1+x(2)*x(2)

```

```

r22=d2*d2+x(2)*x(2)
r0=dsqrt(r12)
r1=dsqrt(r22)
r032=r12*r0
r132=r22*r1
r052=r12*r032
r152=r22*r132
c1=-umu/r032-xmu/r132
c2=3.d0*umu/r052
c3=3.d0*xmu/r152
omex=x(1)-(umu*(-xmu+x(1))/r032)-(xmu*(x(1)+umu)/r132)
omey=x(2)*(1.d0-(umu/r032)-(xmu/r132))
omexx=c1+c2*d1*d1+c3*d2*d2+1.d0
omexy=c2*d1*x(2)+c3*d2*x(2)
omeyy=c1+(c2+c3)*x(2)*x(2)+1.d0
A(1,1)=0
A(1,2)=0
A(1,3)=1
A(1,4)=0
A(2,1)=0
A(2,2)=0
A(2,3)=0
A(2,4)=1
A(3,1)=omexx
A(3,2)=omexy
A(3,3)=0
A(3,4)=2
A(4,1)=omexy
A(4,2)=omeyy
A(4,3)=-2
A(4,4)=0
return
end

```

main_rtbp_flow10b.f was used for the plots of the manifolds (x,y).

Listing 2: main_rtbp_flow10b.f

```

C*****
c
c  MAIN_RTBP_FLOW10b.f
c

```



```

c      We integrate the harmonic oscillator field with Taylor
c      from t=ti up to t=tmax
c      idir= +1 (integration forward in time); =-1 (backward)
c      np= number of intermediate points (apart from the initial one)
c           that we want to write on the file orbit.d. If np=1
c           only the initial and final points are written
c
c      input: xi , ti , tmax , idir , np
c *****
c      implicit real*8 (a-h,o-z)
c      parameter (n=4)
c      dimension xi(n),x(n),A(n,n),RR(n),RI(n),VR(n,n),VI(n,n)
c      dimension v(n),p(2),yf(n)
c      common/param/xmu
c      open(10, file='orbit.d', status='unknown')
c      iregion = -1
c      idir = 1
c      ncrossing = 1
c      ti=0.d0
c      tmax = 6.28
c      np=30
c
c      write(*,*) 'End_of_intervall?'
c      read(*,*) c
c      if (c==0.5) then
c      b = 0.499
c      m=211
c      else
c      b = 0.099
c      m=161
c      endif
c
c      do l=1,m
c      if (l.lt.151) then
c      xmu=l*0.0001
c      else
c      xmu = -1.192+l*0.008
c      endif
c      +l*((c-0.001)/m)
c      call peq(xmu,xl1,xl2,xl3,cl1,cl2,cl3)
c      C=c13

```

```

x(1)=x13
x(2)=0
x(3)=0
x(4)=0
call JacobiMatrix(n,x,xmu,A)
write (*,*) 'A'
  do i=1,n
    write (*,*) (A(i,j),j=1,n)
  enddo
call vapvep(A,n,RR,RI,VR,VI)
c***** Correction of eigenvalues
c   RR(1) = 0
c   RR(2) = 0
c   RR(3) = -0.5016
c   RR(4) = 0.5016
c   RR = SNGL(RR)
c   RI = SNGL(RI)
c   VR = SNGL(VR)
c   VI = SNGL(VI)
k=1
c   do i=1,n
c     if (RR(i).gt.0) then
c       k=i
c     endif
c   enddo

c***** Correction of eigenvectors
c   VR(1,3) = -0.2894
c   VR(2,3) = -0.8457
c   VR(3,3) = 0.1452
c   VR(4,3) = 0.4242
c   VR(1,4) = -0.2894
c   VR(2,4) = 0.8457
c   VR(3,4) = -0.1452
c   VR(4,4) = 0.4242
do i=1,n
v(i) = VR(i,k)
enddo
p(1) = RR(k)
c   p(2) = RI(2)
write (*,*) 'Eigenvalue ', p(1)

```

```

c,      'i*', p(2)
      write(*,*) 'v', (v(i),i=1,n)
      s = 1.d-6
      if(iregion.lt.0) then
      s = -s
      endif
      x = x + s * v
      write(*,*) 'initial_point', (x(i),i=1,n)

c      call jacobi(x,C,xmu,n)

      ti=0
      do j = 1,ncrossing
      t=0.d0
c      write(10,*)t,(x(i),i=1,n)
c      call jacobi(x,C,xmu,n)
      call poinc1(j,xmu,n,m,x,yf,tfinal,idir,ti)
      xdfinal = yf(3)
      write(10,*) xmu, xdfinal
      ti = ti + tfinal
      end do
      end do
      end

c*****Computes Jacobi-Constant
      subroutine jacobi(x,C,xmu,n)
      implicit real*8 (a-h,o-z)
      dimension x(n)
      ro = dsqrt((x(1) - xmu)*(x(1) - xmu))
      rt = dsqrt((x(1) - xmu + 1.d0)*(x(1) - xmu + 1.d0))
      ome =0.5d0*(x(1)*x(1))+(1.d0-xmu)/ro+xmu/rt+0.5d0*xmu*(1.d0-xmu)
      Cnew = 2*ome
      Cdiff = dabs(C - Cnew)
      if (Cdiff.gt.1.d-3) then
      write(*,*) 'Jacobi_constant_not_conserved'
      endif
      end

C*****
c Input:
c n dimension of the vectors yi and yf
c yi initial point

```

```

c idirorig: +1 integration forwards in time; -1 backwards
c yf final point
c tfinal final time
c
C*****
      SUBROUTINE POINC1(j ,xmu,n,m,YI,YF,tfinal ,idirorig ,ti)
      IMPLICIT REAL*8 (A-H,O-Z)
      DIMENSION YI(n),YF(n),DGG(n),F(n)
            icont=0
            idir=idirorig
c
c we assume initial time t=0.
c
c      ti=0.D0
C   DETERMINATION OF THE FIRST PASSAGE OF THE ORBIT THROUGH y=0
C
      CALL SECCIO(YI,GG,DGG)
      IF(DABS(GG).LT.1.D-9)GG=0.d0
      GA=GG
      hab=.1e-16
      hre=.1e-16
      pabs=dlog10(hab)
      prel=dlog10(hre)
      istep=1
c reasonable step:
      pas=0.4d0
      ht=0.d0
      t=ti
c |tmax| must be big enough
1      tmax=t+idir*pas
      CALL taylor_f77_eq_rtbp_var_(t,yi,idir,istep,pabs,prel,
      & tmax,ht,iordre,ifl)
c computation of first integral to be done
C
      CALL SECCIO(YI,GG,DGG)
      IF(GG*GA.LT.0.D0)go to 22
c      write(10,*)t,(yi(ii),ii=1,n)
      GA=GG
      GO TO 1
C
C   REFINEMENT OF THE INTERSECTION POINT YF(*) USING NEWTON'S METHOD

```

```

C...TO_GET_A_ZERO_OF_THE_FUNCTION_GG_(SEE_SUBROUTINE_SECCIO)
C
c...22...continue
c.....icont=icont+1
c.....if_(icont.gt.20)then
c.....write(*,*)'problems finding the section'
c.....stop
c.....endif
c.....CALL_FIELD(xmu,T,YI,N,F)
c.....P=0.D0
c.....DO_3_I=1,N
3.....P=P+F(I)*DGG(I)
c.....H=-GG/P
c_check_p_is_not_(or_very_close_to)_0:_to_be_done
c.....if_(h.ge.0.d0)idir=1
c.....if_(h.lt.0.d0)idir=-1
c.....tmax=t+h
c.....write(*,*)icont,' refining: h and time ',h,tmax
c.....write(*,*)'refining t point ',t,yi(1),yi(2)
c.....CALL_taylor_f77_eq_rtbp_var_(t,yi,idir,istep,pabs,prel,
c.....&tmax,ht,iordre,ifl)
c.....CALL_SECCIO(YI,GG,DGG)
c.....IF(DABS(GG).GT.1.D-13)GO_TO_22
c.....DO_4_I=1,N
4.....YF(I)=YI(I)
c.....tfinal=t
c.....xdfinal=_YF(3)
c_check_first_integral:_to_be_done
c.....write(*,*)'tfinal point time ',tfinal
c.....call_checkperiod(j,tfinal)
c.....write(*,*)(yf(3))
c.....write(10,*)_xdfinal
c.....call_matrix(yf,m,n)
c.....return
c.....t=_tfinal
c.....end

C*****
C.....*
C.....THE_SURFACE_g_OF_SECTION,IN_THIS_CASE

```

```

C_____INPUT_PARAMETERS:
C_____Y(*)_____POINT
C_____OUTPUT_PARAMETERS:
C_____GG_____FUNCTION_THAT_EQUATED_TO_0_GIVES_THE_SURFACE_OF
C_____SECTION
C_____DGG(*)_____GRADIENT_OF_FUNCTION_GG
C_____
C*****
C_____SUBROUTINE_SECCIO(Y,GG,DGG)
C_____IMPLICIT_REAL*8(A-H,O-Z)
C_____DIMENSION_Y(2),DGG(2)
C_____GG=Y(2)
C_____DO_1_I=1,2
_1_____DGG(I)=0.D0
C_____DGG(2)=1.d0
C_____RETURN
C_____END

C
C_FIELD.F
C
C*****
C_____EQS_OF_MOTION_IN_synodical_VARIABLES
C_____X_____TIME
C_____Y(*)_____POINT_(Y(1),Y(2),...Y(n))
C_____NEQ_____NUMBER_OF_EQUATIONS
C_____OUTPUT_PARAMETERS:
C_____F(*)_____VECTOR_FIELD
C
C*****
C_____subroutine_field(xmu,t,x,neq,f)
C_____implicit_real*8_(a-h,o-z)
C_____dimension_x(neq),f(neq)
c
C_____umu=1.d0-xmu
C_____d1=x(1)-xmu
C_____d2=x(1)+umu
C_____r12=d1*d1+x(2)*x(2)
C_____r22=d2*d2+x(2)*x(2)

```

```

.....r0=dsqrt ( r12)
.....r1=dsqrt ( r22)
.....r032=r12*r0
.....r132=r22*r1
.....r052=r12*r032
.....r152=r22*r132
.....c1=-umu/r032-xmu/r132
.....c2=3.d0*umu/r052
.....c3=3.d0*xmu/r152
.....omex=x(1)-(umu*(-xmu+x(1))/r032)-(xmu*(x(1)+umu)/r132)
.....omey=x(2)*(1.d0-(umu/r032)-(xmu/r132))
.....omexx=c1+c2*d1*d1+c3*d2*d2+1.d0
.....omexy=c2*d1*x(2)+c3*d2*x(2)
.....omeyy=c1+(c2+c3)*x(2)*x(2)+1.d0
.....f(1)=x(3)
.....f(2)=x(4)
.....f(3)=2.*x(4)+omex
.....f(4)=-2.*x(3)+omey
.....return
.....end
c***** Jacobi-Matrix of x
.....subroutine JacobiMatrix(n,x,xmu,A)
.....implicit real*8(a-h,o-z)
.....dimension x(n),A(n,n)
c
.....umu=1.d0-xmu
.....d1=x(1)-xmu
.....d2=x(1)+umu
.....r12=d1*d1+x(2)*x(2)
.....r22=d2*d2+x(2)*x(2)
.....r0=dsqrt ( r12)
.....r1=dsqrt ( r22)
.....r032=r12*r0
.....r132=r22*r1
.....r052=r12*r032
.....r152=r22*r132
.....c1=-umu/r032-xmu/r132
.....c2=3.d0*umu/r052
.....c3=3.d0*xmu/r152
.....omex=x(1)-(umu*(-xmu+x(1))/r032)-(xmu*(x(1)+umu)/r132)
.....omey=x(2)*(1.d0-(umu/r032)-(xmu/r132))

```

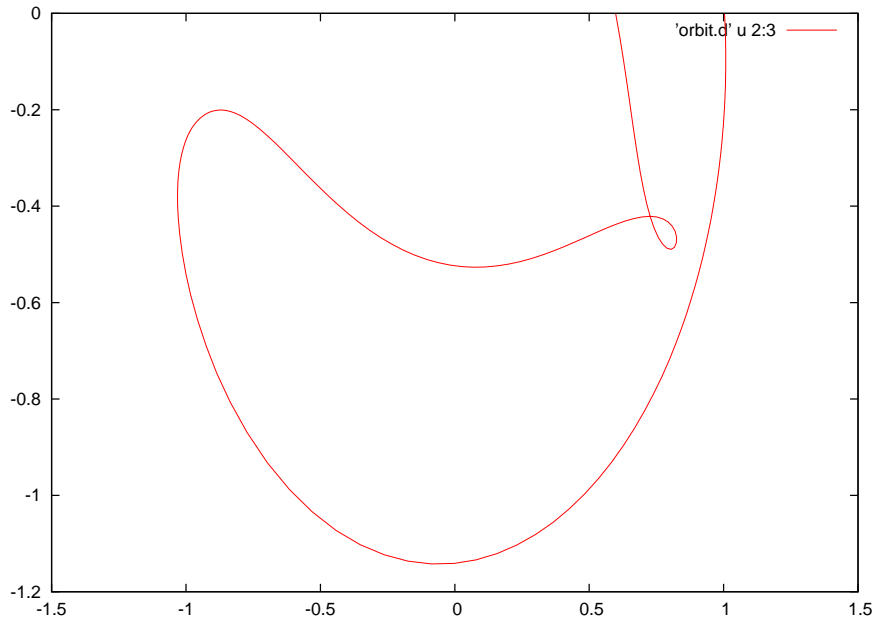
```

.....omexx=c1+c2*d1*d1+c3*d2*d2+1.d0
.....omexy=c2*d1*x(2)+c3*d2*x(2)
.....omeyy=c1+(c2+c3)*x(2)*x(2)+1.d0
.....A(1,1)=0
.....A(1,2)=0
.....A(1,3)=1
.....A(1,4)=0
.....A(2,1)=0
.....A(2,2)=0
.....A(2,3)=0
.....A(2,4)=1
.....A(3,1)=omexx
.....A(3,2)=omexy
.....A(3,3)=0
.....A(3,4)=2
.....A(4,1)=omexy
.....A(4,2)=omeyy
.....A(4,3)=-2
.....A(4,4)=0
.....return
.....end

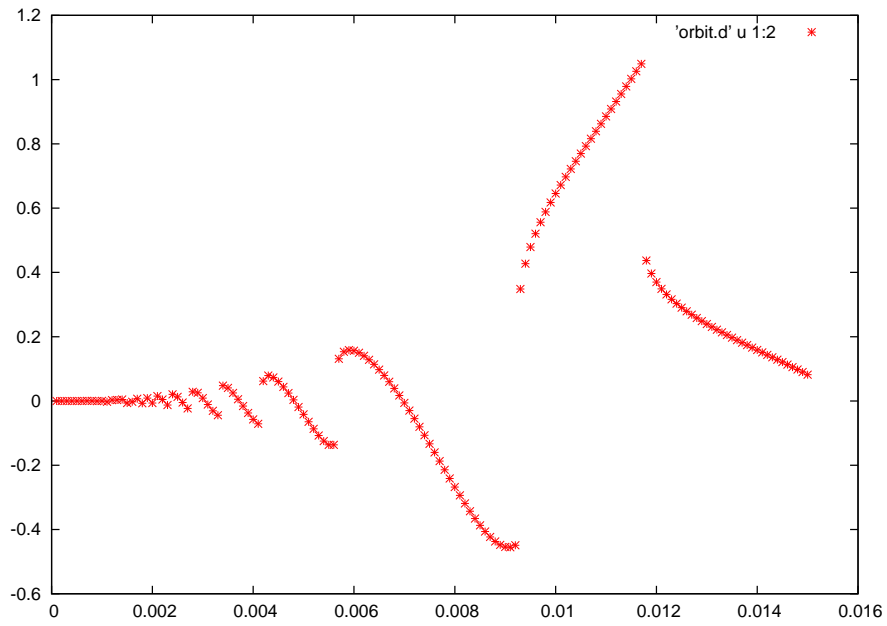
```


2 Plots

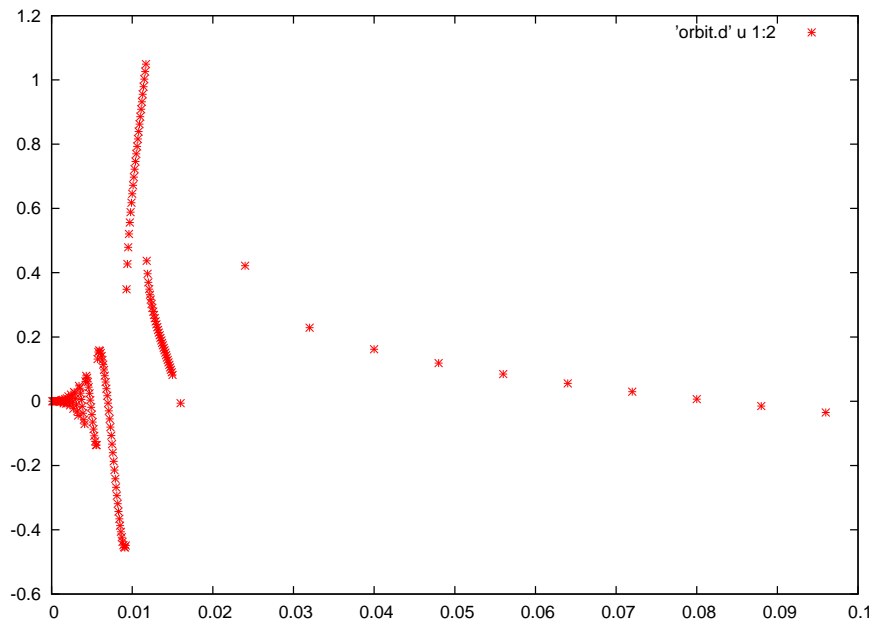
2.1 Orbit (x,y) of $\mu = 0.008$



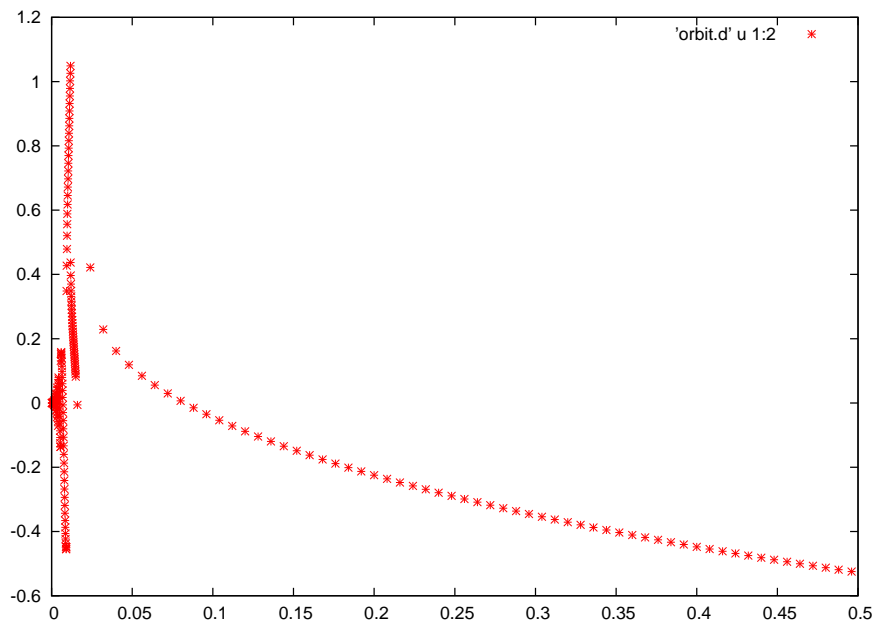
2.2 Graph (x_{μ}, x') for μ in $(0.001, 0.015)$



2.3 Graph (x_{μ}, x') for μ in $(0.001, 0.1)$

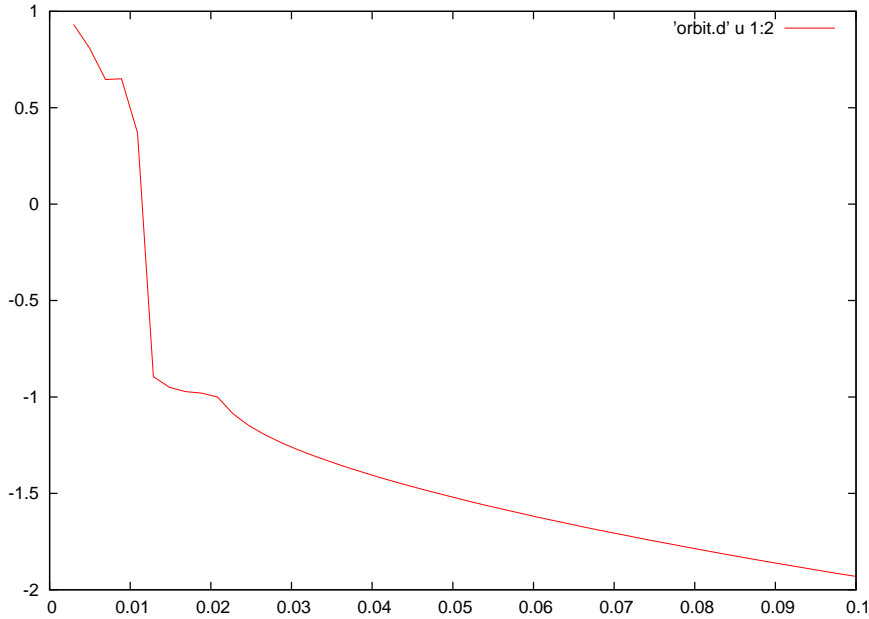


2.4 Graph (x_{μ}, x') for μ in $(0.001, 0.5)$



3 Optional Part

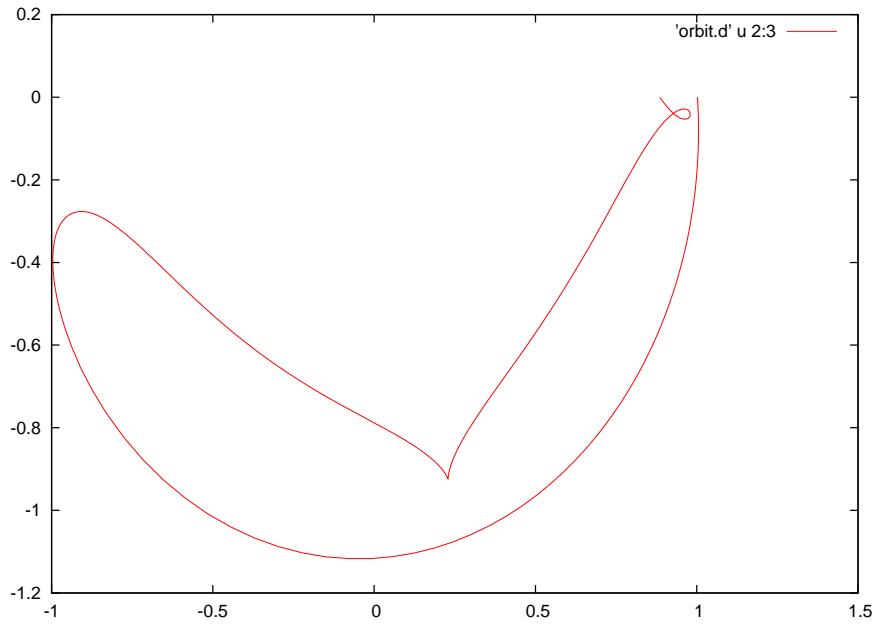
3.1 Curve (mu,x1)



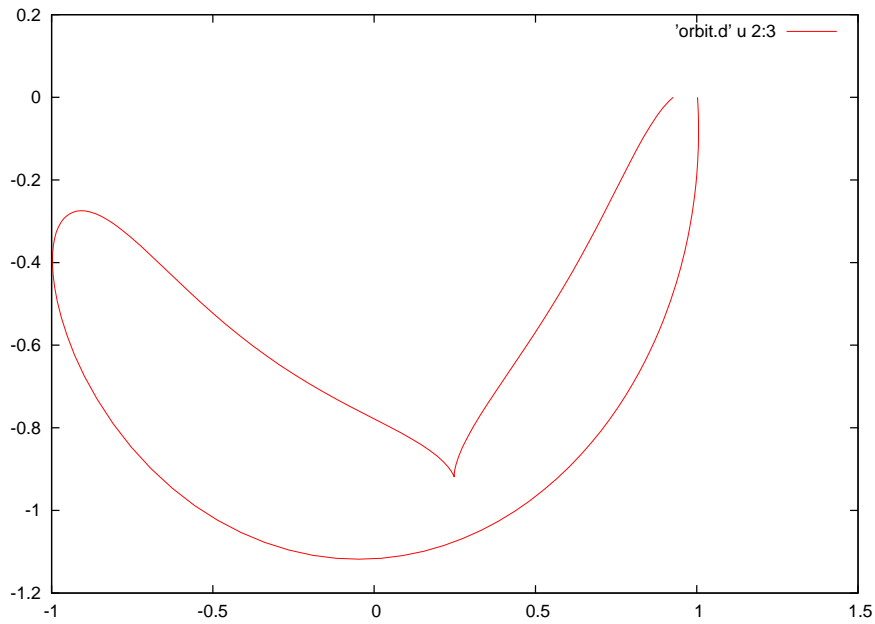
The value of x_1 at the first crossing is decreasing in μ . It starts with $x_1 = 1$, becomes negative approximately at $\mu = 0.015$ and decreases further until almost $x_1 = -2$ at $\mu = 0.1$. The curve is not always strictly decreasing. Approximately at $\mu = 0.1$ x_1 is slightly increasing as one can also see on the plots for $\mu = 0.0056$ to $\mu = 0.0057$. What the plot not shows is that x_1 is still decreasing in μ as one may see on the plots for $\mu = 0.01179$ to $\mu = 0.083$.

3.2 Part 3

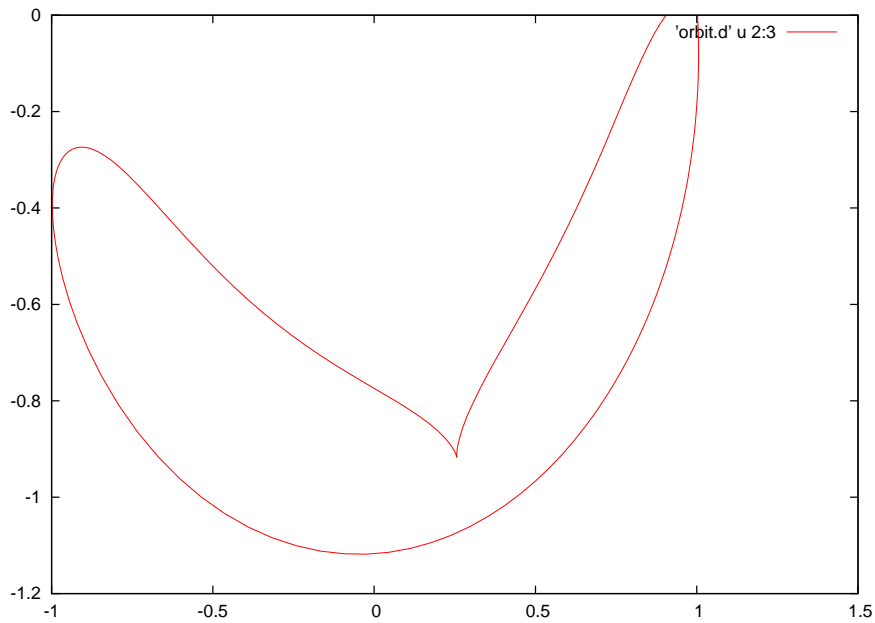
3.2.1 (x,y)-manifold for $\mu=0.0056$



3.2.2 (x,y)-manifold for $\mu=0.00567$



3.2.3 (x,y)-manifold for $\mu=0.0057$

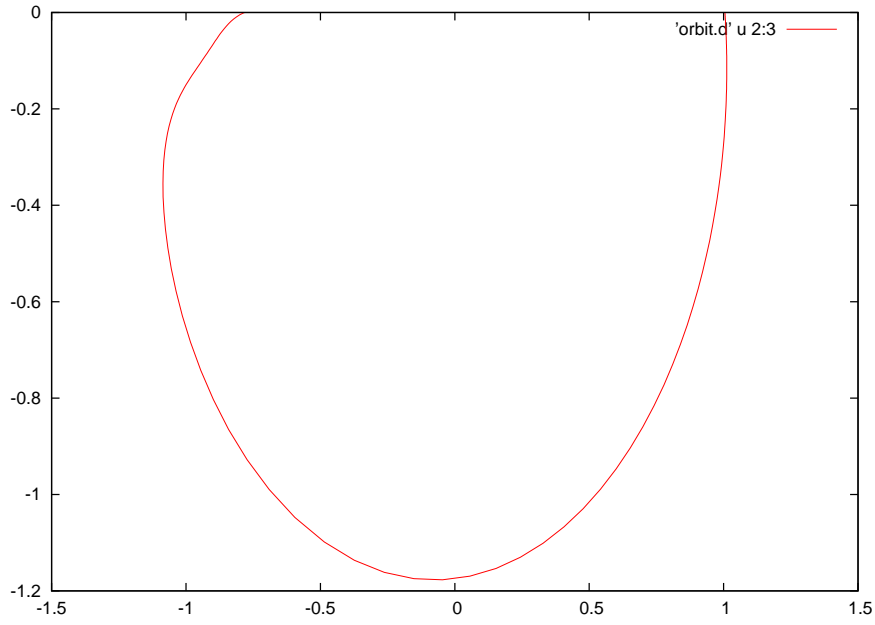


The graphs for $\mu = 0.0056$ to $\mu = 0.0057$ show the parts where x_1 at the first crossing is

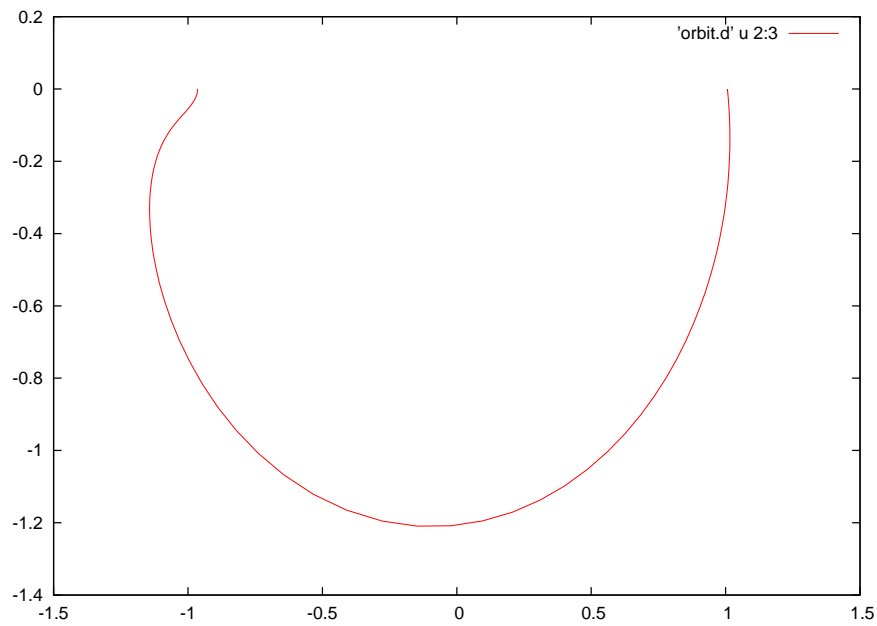
slightly increasing.

3.3 Part 4

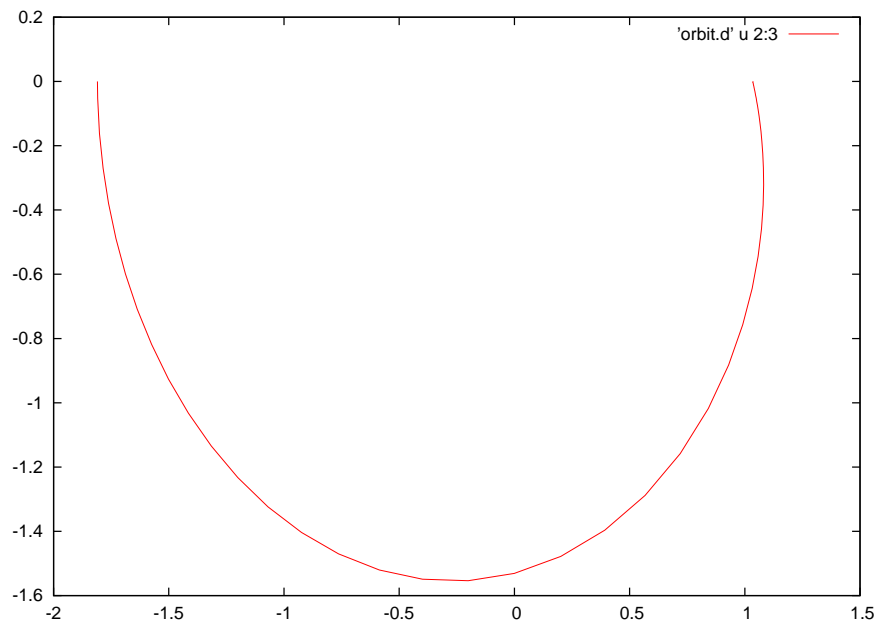
3.3.1 (x,y)-manifold for $\mu=0.01179$



3.3.2 (x,y)-manifold for $\mu=0.0159375$



3.3.3 (x,y)-manifold for $\mu=0.083$



The graph shows a part of an orbit which opens more when μ increases, because the initial

x increases and x_1 at the crossing decreases.